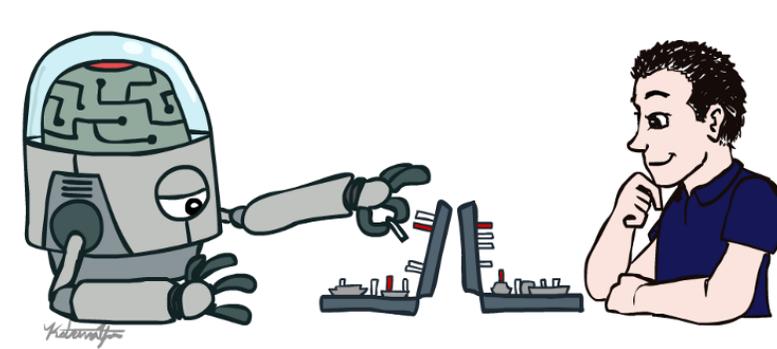


Artificial Intelligence Intro and Agents



CS 444 – Spring 2021

Dr. Kevin Molloy

Department of Computer Science

James Madison University

Meet and Greet

Who is this person?

- Grew up in Newport News. Last 20 years in Northern Virginia
- Got my PhD in 2015 in computer science with a focus on robotics, artificial intelligence and structural biology (proteins)
- Work/lived in southern France (Toulouse) for \approx 2 years as a research scientist
- My 3rd year at JMU



Course Information

- Communication

- Announcements on webpage and Canvas
- Questions? Discussion on **Piazza**
- Email: molloykp@jmu.edu
- Office hours are posted on Canvas.

Course Delivery:

- Lectures: zoom (see canvas for link)
- Review of homework via Youtube channel
- Autograded homework and projects via <https://autolab.cs.jmu.edu>

- Course Assignment and Topics

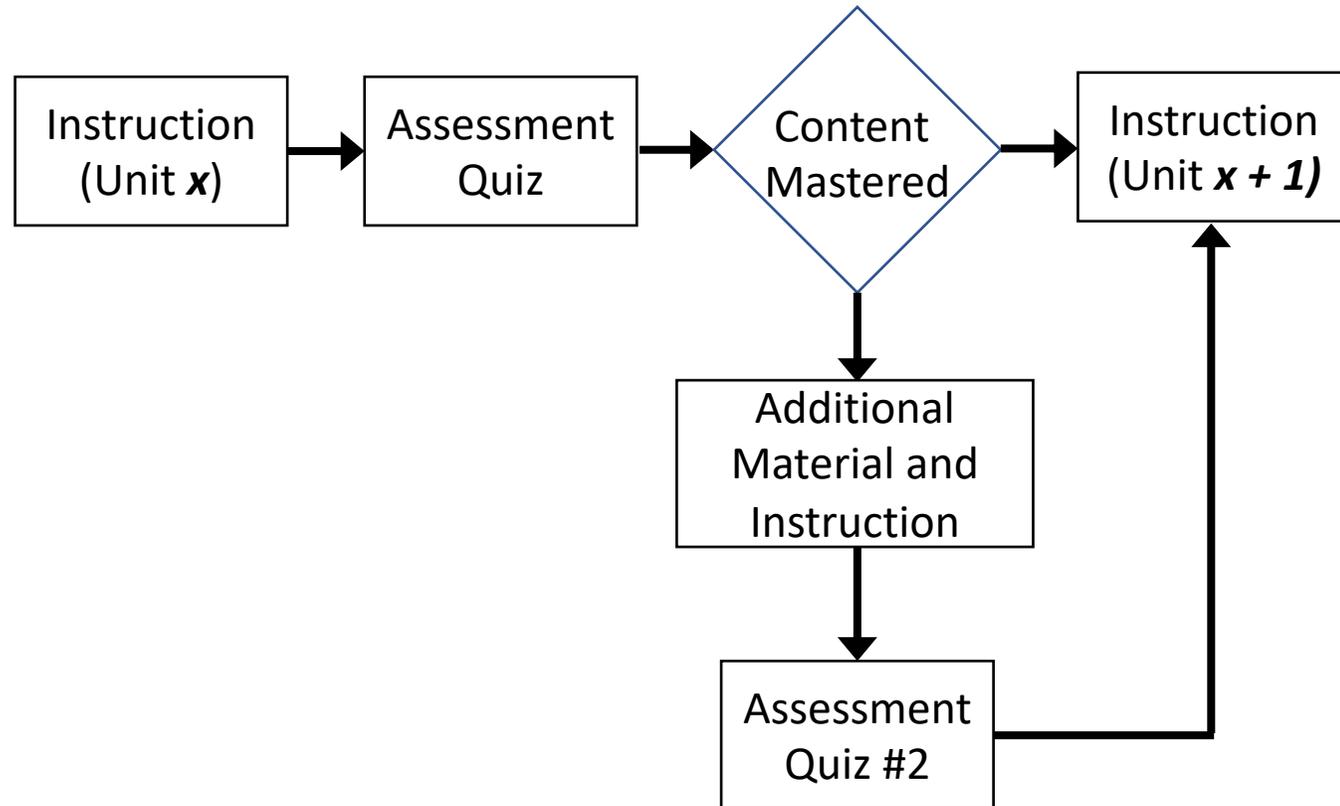
- Class calendar is available at https://w3.cs.jmu.edu/molloykp/cs444/cs444_2021Spring/cs444_Calendar.php
- All due dates are in Canvas

- Programming Assignments PAs

- Between 6 and 8
- Python Programming Language
- Students will be expected to present their findings/results to the class (at least once in the semester). This may be done live or via video.
- PA 0 due next Tuesday

Mastery Learning Model

- Quiz each week on material
- If you score well, your done.
- If you are not happy with your score, you can take another quiz on the subject the following week.
- Starting around week 5 or 6, the quiz will consist of the current material plus material from 5 or 6 weeks ago.
- Approximately 12 of these quizzes. No exams.



Course Information

- Prerequisites:

- We will be using some basic statistics and linear algebra. Review material will be provided.
- We will use a little calculus in this book for analysis.

- Textbook:

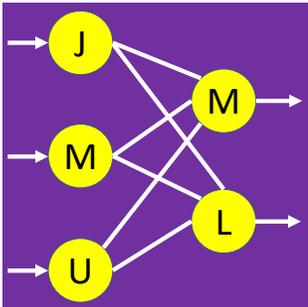
- Artificial Intelligence, Forth Edition by Stuart Russell and Peter Norvig
- The lecture slides and other reading material will be posted.

- Grading

Task	Number	Percent
Weekly Quizzes	12	50%
Programming Assignments	6 to 8	35%
Homework, Labs, Participation	6 to 8	15%

Why Take This Class?

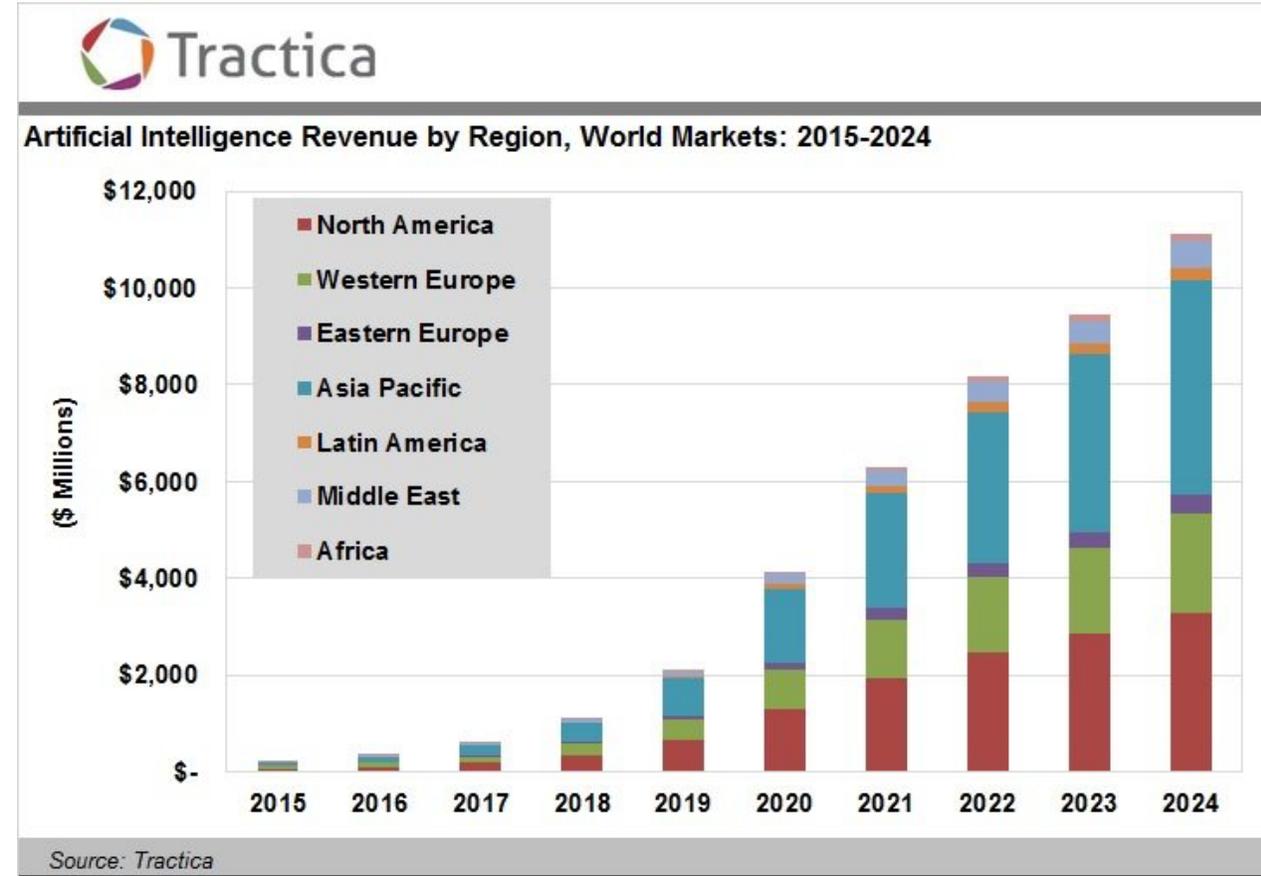
- You want to learn more about AI
- You want to get an exciting job



CS 445 Machine Learning

JMU AI and Machine Learning Seminar Series

Third Thursday of Each Month (4:15 – 5:00 pm)



Important This Week

- **Register on Autolab** (<https://autolab.cs.jmu.edu>). You will need to use VPN if connecting to Autolab from off Campus (VPN instructions are on the resources page on the class web site).
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- **PA 0** is out and due next Tuesday, January 26th.
- **Quiz 0** will be published on Canvas after class on Thursday and will be due Friday, January 22nd @ 5:00 pm. The quiz will be timed (20 minutes to complete once started). Topics for Quiz 0 are posted on the class website.

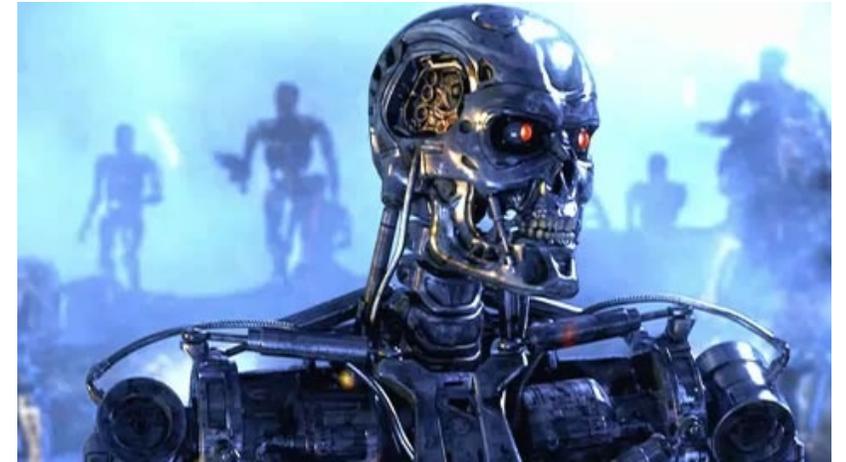
Objectives For Today

- What is AI?
- What can AI do?
- What are we going to do in this course?
- Introduction to AI agents

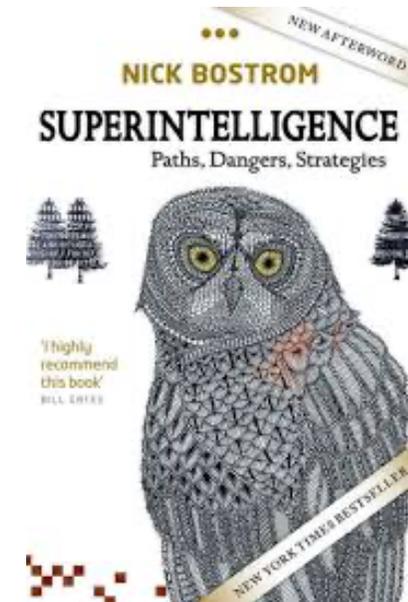
What is AI?

Sci-Fi tells us AI:

- can be nice (R2D2, C3PO)
- can be scary (terminator)



I am reading this book now,
and so far, it is good.



What is Intelligence?

Are we intelligent? Are animals intelligent?

Take a few moments and write down your definition of intelligence

My definition

A computational model/process that:

- solve a problem that does not have an efficient algorithm and requires "intuition"
- Reasons using facts (and allows new facts to be learned)
- Learns a process by given a set of examples (this is a specialty of AI known as machine learning or statistical inference).

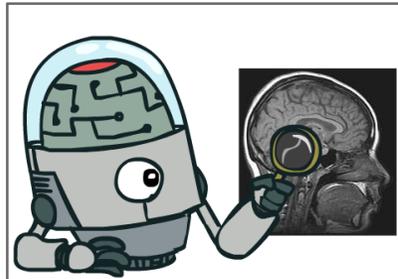
What is AI?

Science of making machines that:

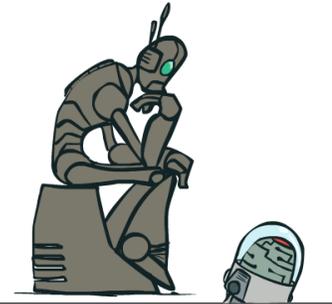
What is AI?

Science of making machines that:

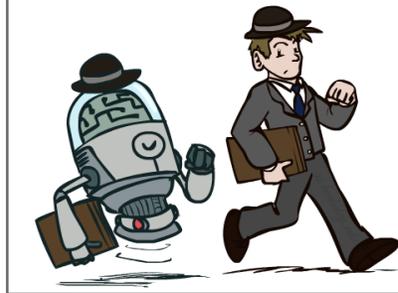
Think like people



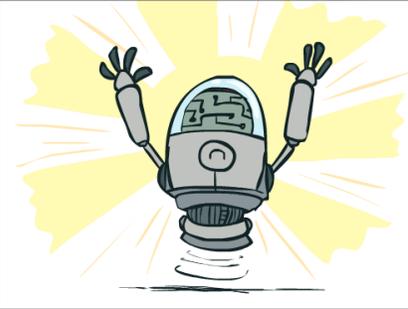
Think rationally



Act like people



Act rationally



Rational Decisions? What are these?

We use the term **rational** in a very specific, technical way:

- Rational: maximally achieving pre-defined goals
- Rationality only concerns what decisions are made (not the thought process behind how the decisions are made)
- Goals are expressed in terms of the **utility** of outcomes
- Being rational means **maximizing your expected utility**

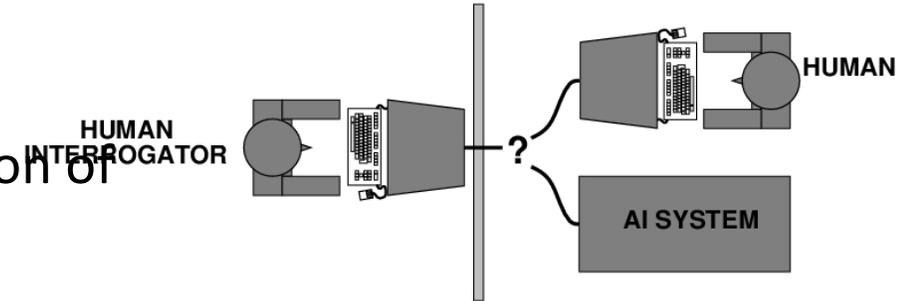
Might think of AI as being the study of **computational rationality**¹

Quantifying Artificial Intelligence – The Turing Test

To be intelligent is to act humanly. – Alan Turing

Turing Test

- Turing focused on “acting like a human” as an operational definition of artificial intelligence: Turing (1950). “Computing machinery and intelligence”
- Proposed the “imitation” game as a test for a hidden intelligent artifact who could be fed visual and material information
- **Objective:** fool a human 30% of the time in a 5-minute test

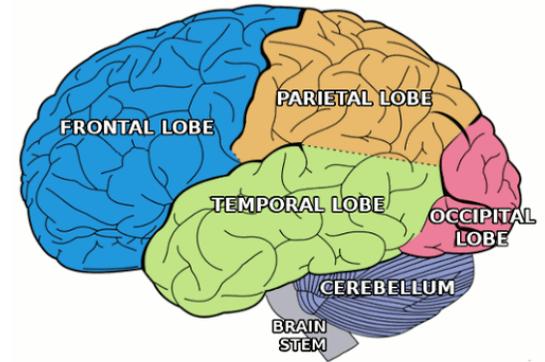


This test introduced major components of AI: knowledge, reasoning, language, understanding, learning (computer vision, robotics). Turing predicted this would be reached by the year 2000.

- **Problem:** Turing test is not reproducible, informative/constructive, or amenable to mathematic analysis.
- **Weak vs Strong AI argument:** One can simulate intelligence but not possess it.

Our Brains

- Human brains are very good at making rational decisions, but not perfect
- Brains are not as modular as software, so hard to reverse engineer
- "Brains are to intelligence as wings are to flight"



	Supercomputer	Personal Computer	Fly	Human Brain
Computational Units	10 ⁶ GPUs and CPUs 10 ¹⁵ transistors	8 CPU cores 10 ¹⁰ transistors	10 ⁵ neurons	10 ⁶ columns 10 ¹¹ neurons
Storage Units	10 ¹⁶ bytes RAM 10 ¹⁷ bytes disk	10 ¹⁰ bytes RAM 10 ¹² bytes disk	10 ⁷ synapses	10 ¹¹ neurons 10 ¹⁴ synapses
Cycle time	10 ⁻⁹ secs	10 ⁻⁹ secs	10 ⁻³ secs	10 ⁻³ secs
Operations/sec	10 ¹⁸	10 ¹⁰	10 ¹⁰	10 ¹⁷

If each synapse is 1 FLOP (fire/not fire once per second),

Then human brain requires 10¹⁵ flops = 1 petaflop

100,000 CPUs

Amazon EC2 costs
\$5,000 per hour

Summarized History of AI

- 1940-1950: Early days
 - 1943: McCulloch & Pitts: Boolean circuit model of brain
 - 1950: Turing's "Computing Machinery and Intelligence"
- 1950—70: Excitement: Look, Ma, no hands!
 - 1950s: Early AI programs, including Samuel's checkers program, Newell & Simon's Logic Theorist, Gelernter's Geometry Engine
 - 1956: Dartmouth meeting: "Artificial Intelligence" adopted
 - 1965: Robinson's complete algorithm for logical reasoning
- 1970—90: Knowledge-based approaches
 - 1969—79: Early development of knowledge-based systems
 - 1980—88: Expert systems industry booms
 - 1988—93: Expert systems industry busts: "AI Winter"
- 1990—: Statistical approaches
 - Resurgence of probability, focus on uncertainty
 - General increase in technical depth
 - Agents and learning systems... "AI Spring"?

- 2021—: Where are we now?

What Can AI Do?

Quiz: Which of the following can be done by AI?

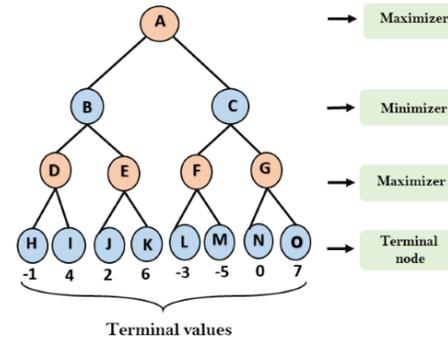
- ✓ • Play a decent game of Jeopardy?
- ✓ • Play a decent game of table tennis?
- ✓ • Drive safely along a curving mountain road?
- ? • Drive safely along Reservoir Street?
- ✓ • Buy a week's worth of groceries online?
- ✗ • Buy a week's worth of groceries at a store?
- ? • Discover and prove a new mathematical theorem?
- ✗ • Converse successfully with another person?
- ? • Perform a surgical operation?
- ✓ • Put away the dishes and fold the laundry?
- ✓ • Translate spoken Chinese into spoken English?
- ✗ • Write an intentionally funny story?



Course Topics

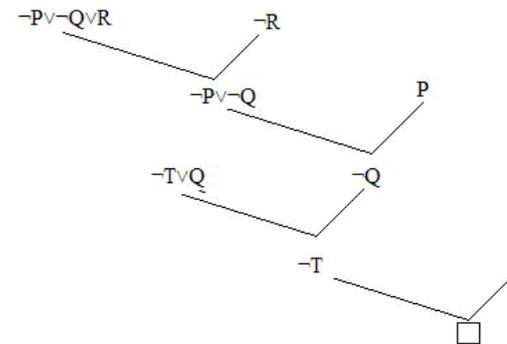
Part I: Making decisions

- Fast search and planning
- Constraint satisfaction
- Adversarial and Uncertain search



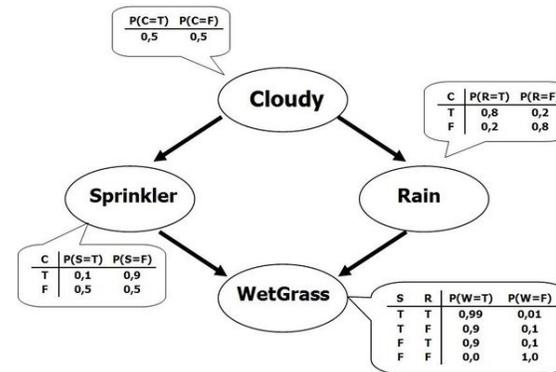
Part II: Representing Knowledge and Logic

- Propositional Logic and representation
- First-order logic and reasoning



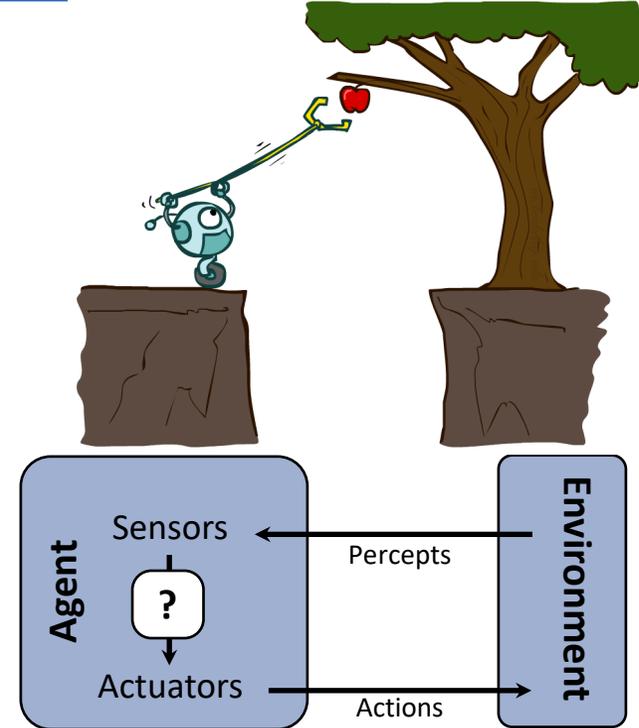
Part III: Reasoning under Uncertainty

- Markov Models
- Bayes nets



Designing Rational Agents

- An **agent** is an entity that *perceives* and *acts*.
- A **rational agent** selects actions that maximize its (expected) **utility** given the percepts sequence to date.
- Characteristics of the **percepts, environment, and action space** dictate techniques for selecting rational actions (PEAS)
- **This course is about:**
 - General AI techniques for a variety of problem types
 - Learning to recognize when and how a new problem can be solved with an existing technique



Rational \neq omniscient

- Percepts may not supply all relevant information

Rational \neq clairvoyant

- Action outcomes may not be as expected

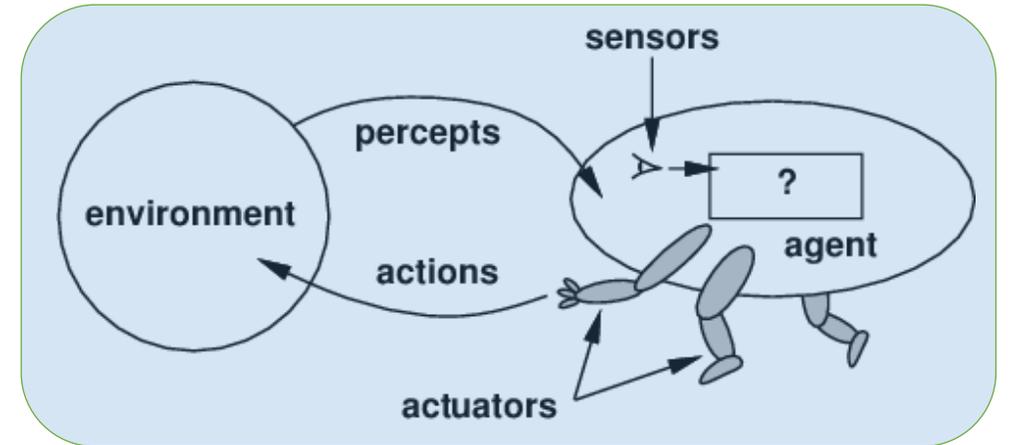
Hence, rational does not always equal successful.

Agents and Environments

Agents include humans, robots, softbots, thermostats, etc.

The **agent function** maps from percept histories to actions: $f : \mathcal{P}^* \rightarrow \mathcal{A}$

The **agent program** runs on the physical **architecture** to produce f .



Environment Types

Do the agent's sensors give complete information (relevant to the choice of action) about the estate of the environment at each point in time?

- Fully vs. partially-observable

Does the agent operate in an environment with other agents?

- Single vs. multi-agent (competitive, cooperative)

Is the next state of the environment complete determined by the current state and agent action?

- Episodic vs. sequential

Can the environment change while the agent is deliberating?

- Static vs dynamic

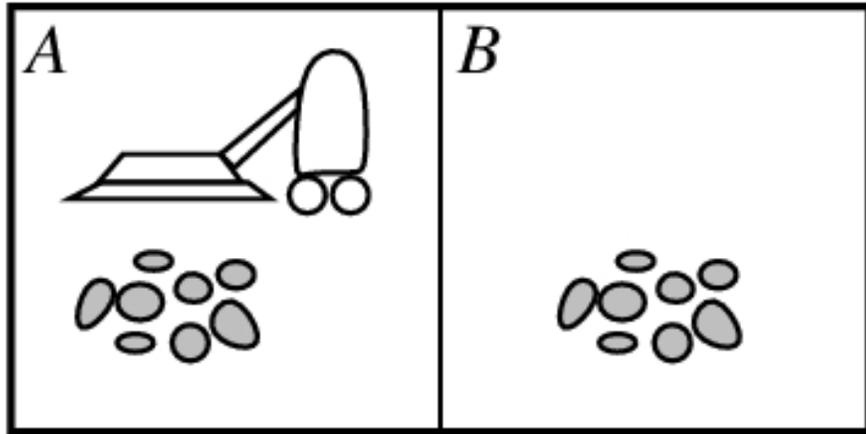
What is the domain of values for variables racking environment state, agent state, and time?

- Discrete vs. continuous

Does the agent know outcomes of all its actions?

- Known vs unknown

Vacuum-cleaner World and Agent Types

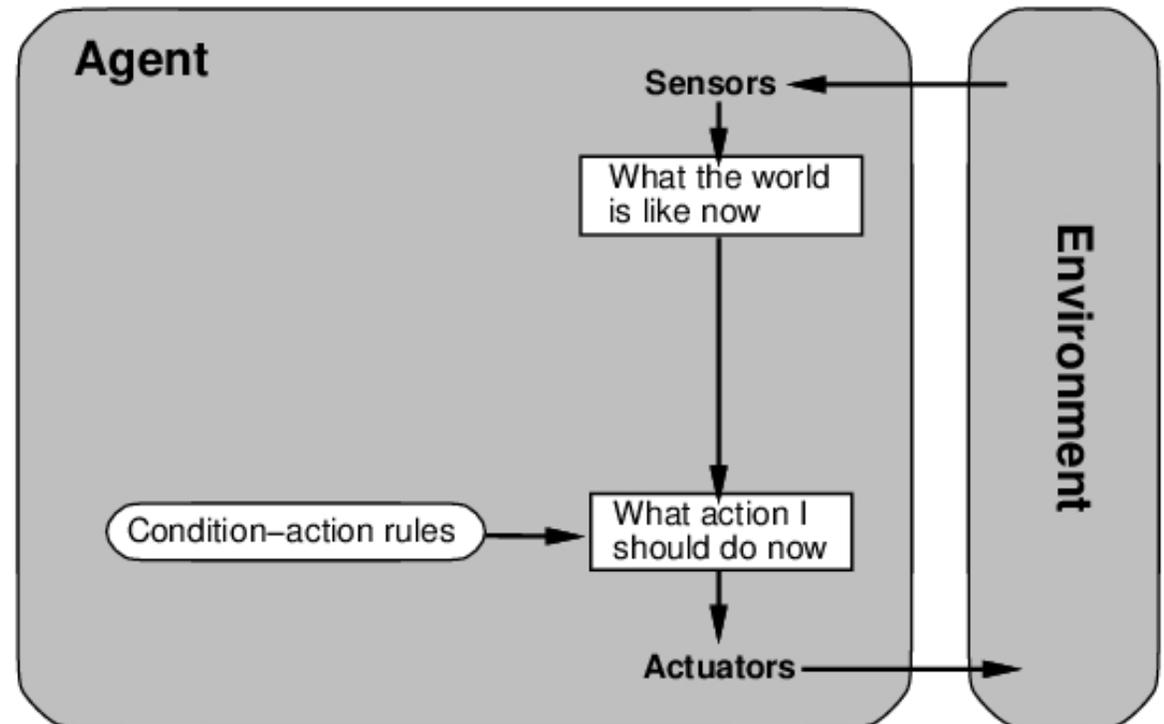


Percepts: location and contents, e.g., [A, Dirty]

Action: *Left, Right, Suck (remove the dirt), NoOp*

Four basic types of agents:

- Simple reflex agents
- Reflex agents w/state
- Goal-based agents
- Utility-based agents



A simple reflex agent

Reflex Agent Example

```
function REFLEX-VACUUM-AGENT ([location, status])  
returns an action  
    if status = Dirty then return Suck  
    else if location = A then return Right  
    else if location = B then return Left
```

Can a reflex agent be rational?

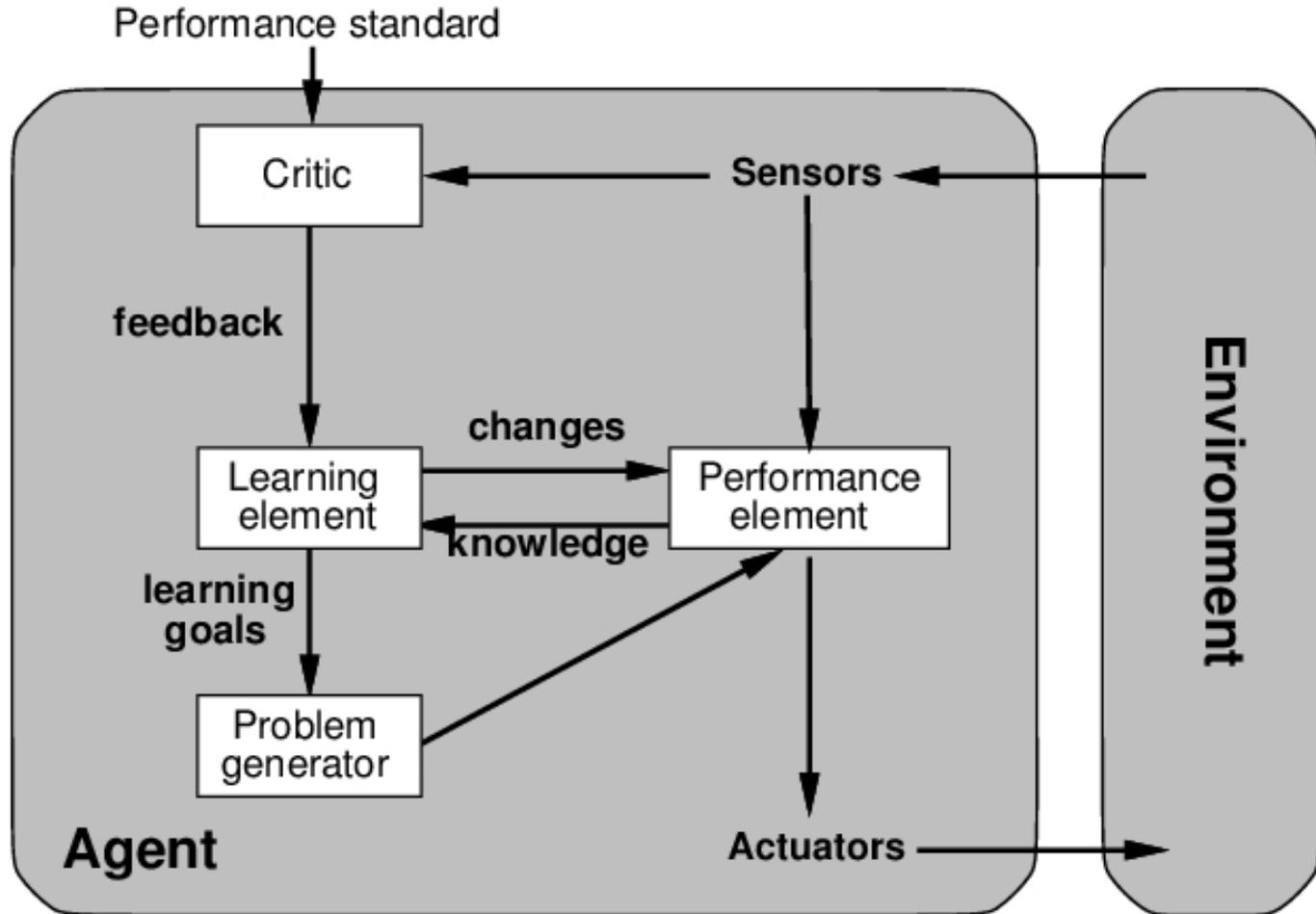
A rational agent:

chooses which ever action maximizes the expected value of the performance measure given the percept sequence to date.

Depends, on the performance measure:

- 1 pt for each clean square in each time step
- Geography is known *a priori*
- Agent correctly perceives its location and dirt, and the cleaning mechanism works 100% of the time.

Learning-based agents



Learning-based agents:

- Performance elements was the "entire" agent previously (accepted sensor input and commanded the actuators).
- Learning elements gets feedback from the critic and changes the performance element.
- Problem generator is the "lets try this and see what happens". Let's explore the impact of other actions.
- Deepmind's AlphaGo and other recent breakthroughs use these types of agents.

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